



# END TO END NEEDS FOR AUTONOMOUS VEHICLES

NORM MARKS | SEPT. 6, 2018

# THE MOST EXCITING TIME IN TECH HISTORY

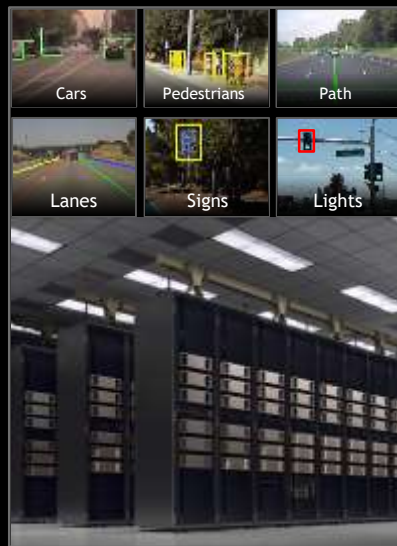


**NVIDIA GPU**

# END-TO-END SYSTEM FOR AV



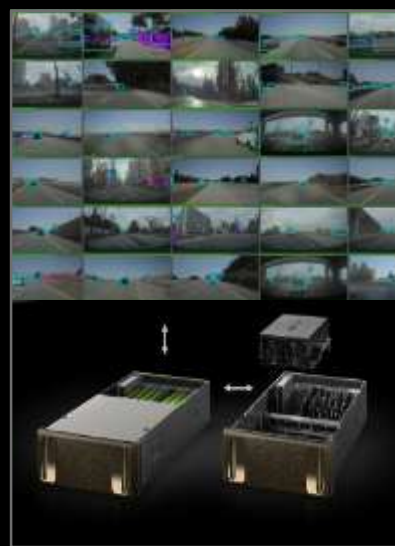
COLLECT DATA



TRAIN MODELS



SIMULATE



RE-SIMULATE



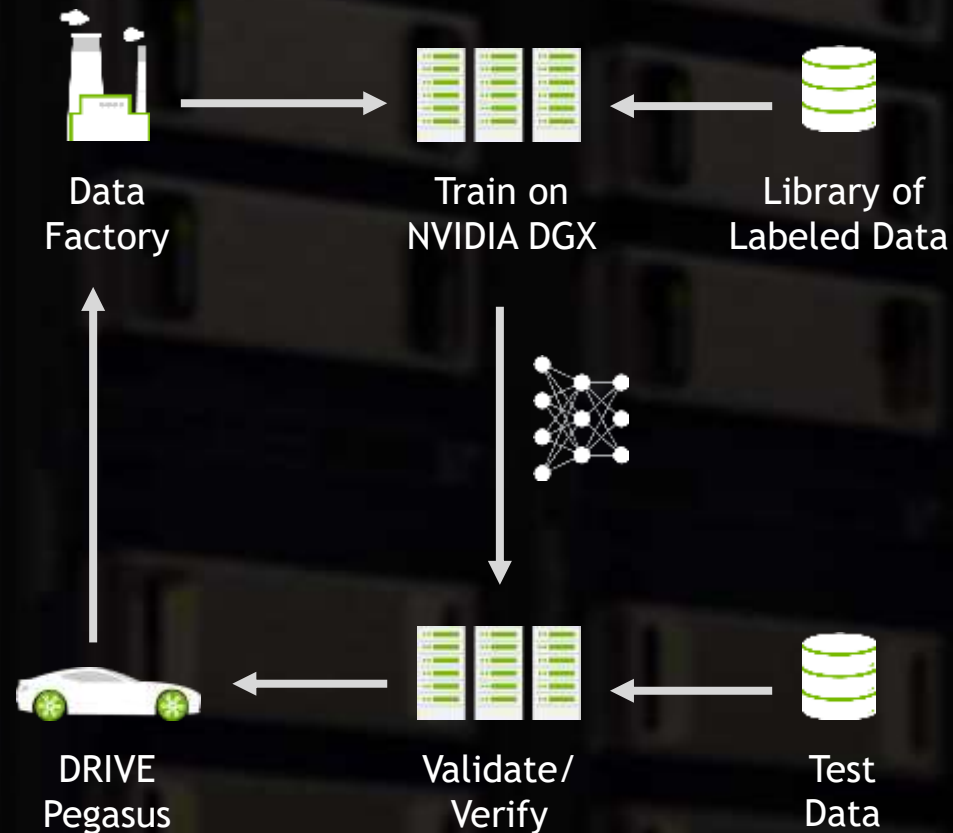
MAPPING

# NVIDIA PERCEPTION INFRASTRUCTURE

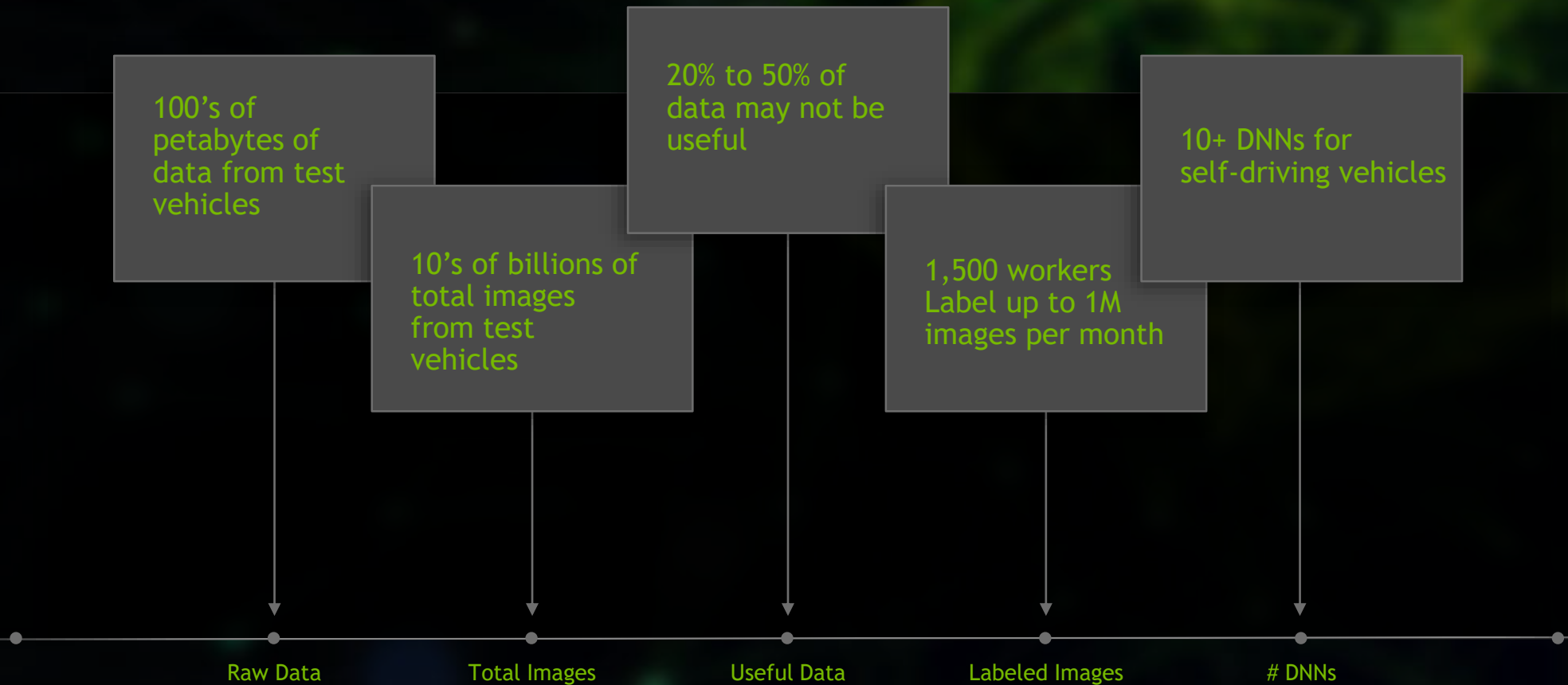
## LARGE-SCALE DEEP LEARNING MODEL DEVELOPMENT

Workflow, Tools, Supercomputing Infrastructure  
Data Ingest, Labeling, Training, Validation, Adaptation  
Automation, Best Model Discovery, Traceability,  
Reproducibility  
Purpose-built for Safety Standards of Automotive

“Data is the new source code”

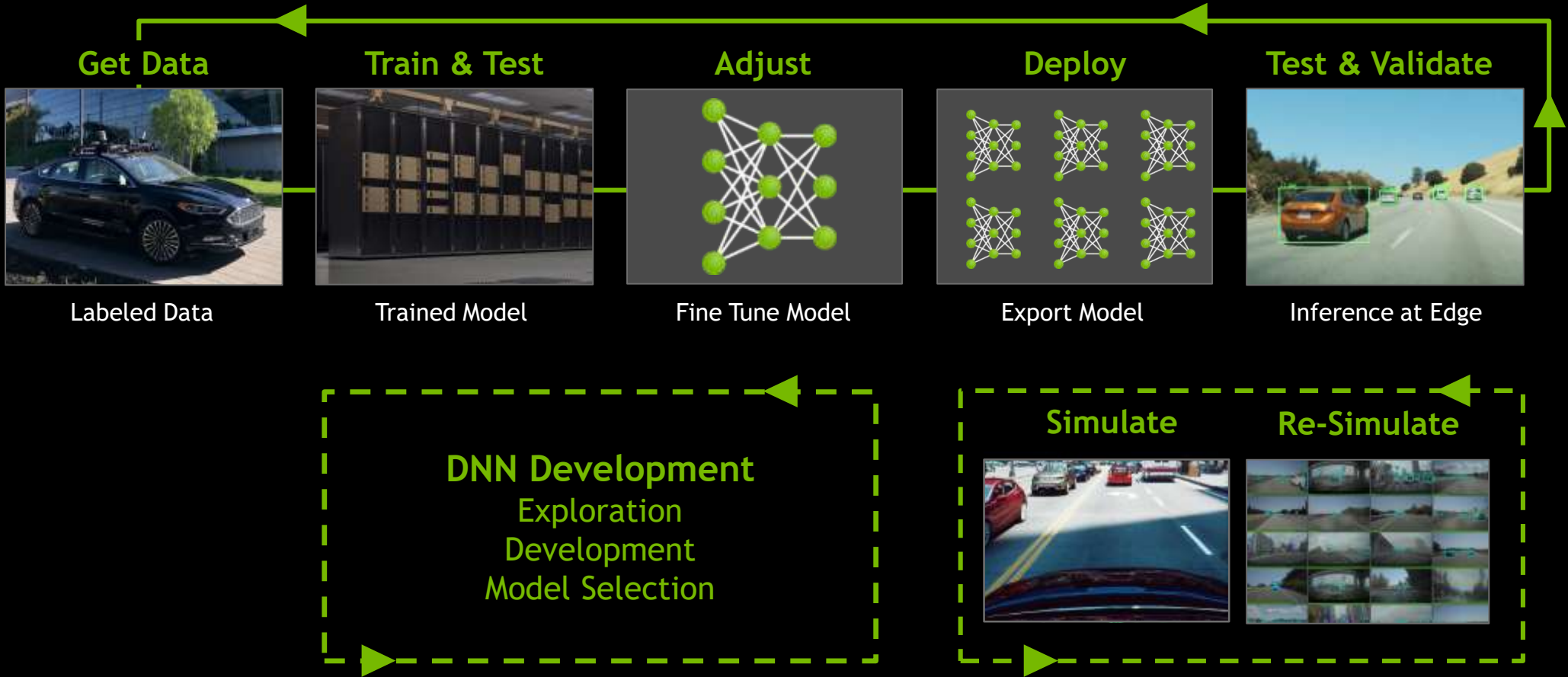


# DATA COLLECTION AND LABELING FOR AI



Source: Data from test fleets of 50-100 cars

# AI FOR SELF-DRIVING WORKFLOW



# AI FOR SELF-DRIVING



Perception



Free Space Perception



Distance Perception



Weather



LIDAR Perception



Camera-based Mapping



Camera Localization to HD Map



LIDAR Localization to HD Map



Path Perception

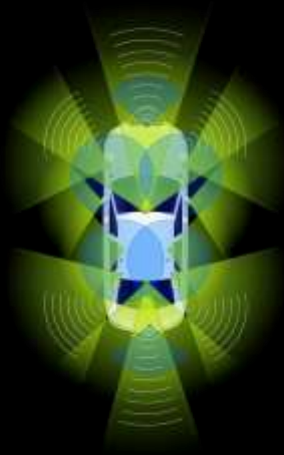
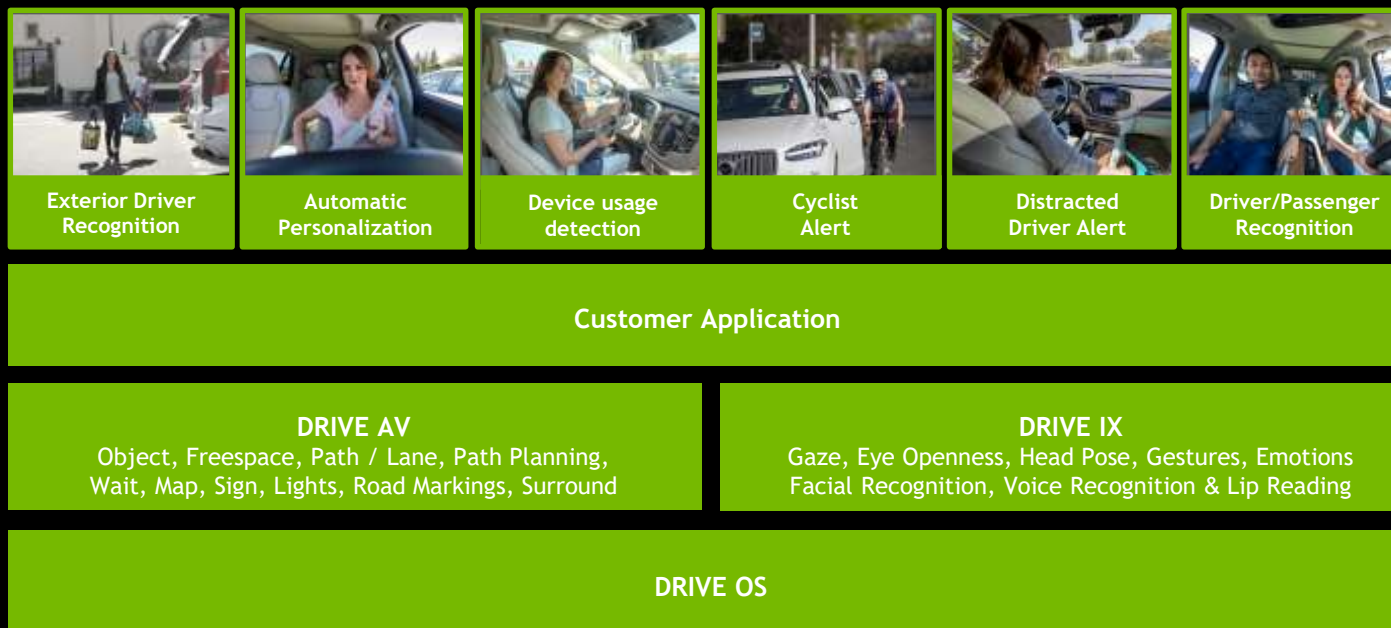


Scene Perception





# AI OUTSIDE AND INSIDE THE VEHICLE



# MANY THINGS TO LEARN



“ Autonomous vehicles need to be driven more than 11 billion miles to be 20% better than humans. With a fleet of 100 vehicles, 24 hours a day, 365 days a year, at 25 miles per hour, this would take 518 years. ”

Rand Corporation, Driving to Safety

# SIMULATION

## THE PATH TO BILLIONS OF MILES

World drives trillions of miles each year.

U.S. has 770 accidents per billion miles.

A fleet of 20 test cars cover 1 million miles per year.



# NVIDIA DRIVE SIM AND CONSTELLATION

AV VALIDATION SYSTEM



Virtual Reality AV Simulator

Same Architecture as DRIVE Computer

Simulate Rare and Difficult Conditions, Recreate  
Scenarios, Run Regression Tests, Drive Billions of  
Virtual Miles

1,000's Constellations Drive Billions of Miles per Year



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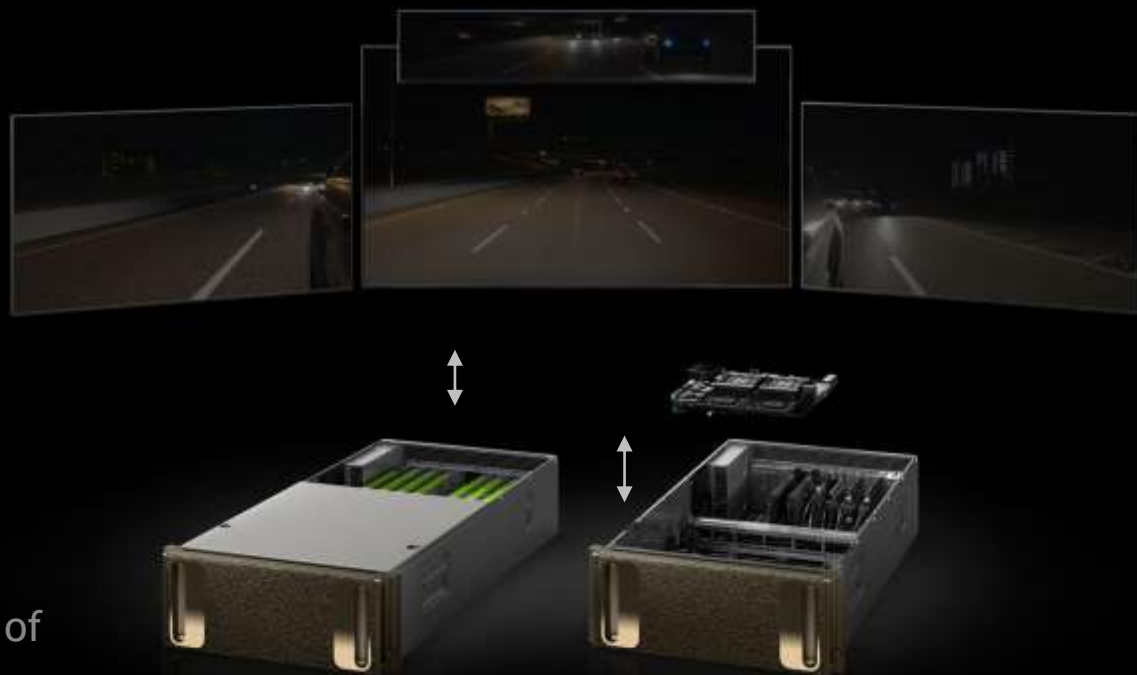
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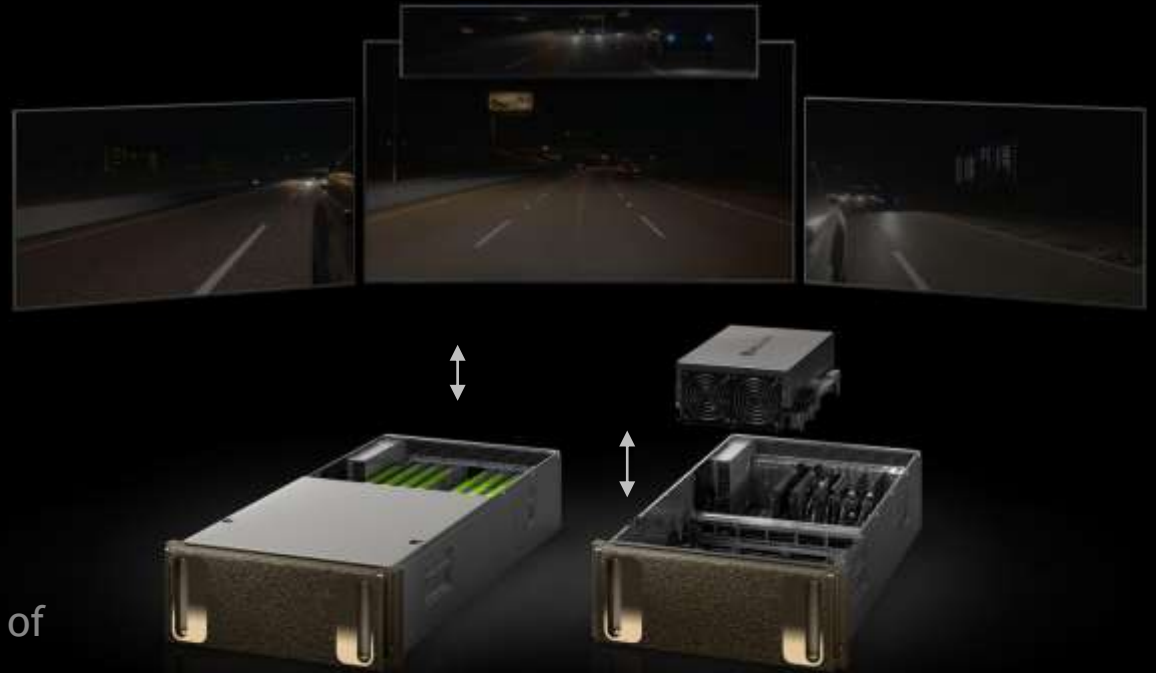
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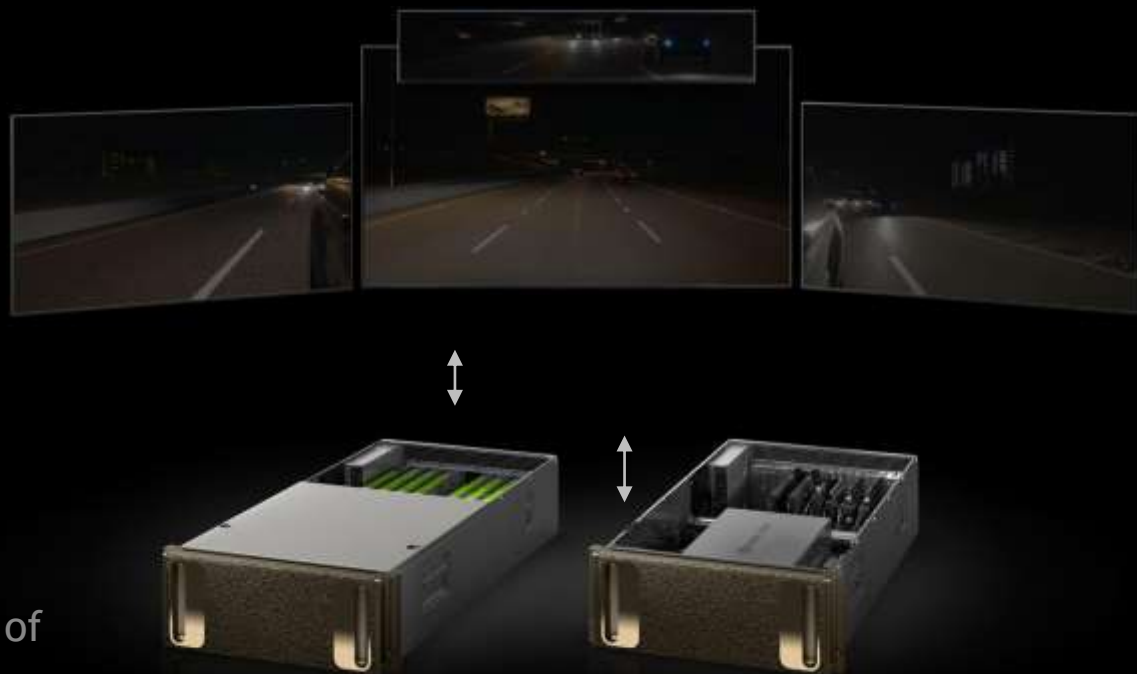
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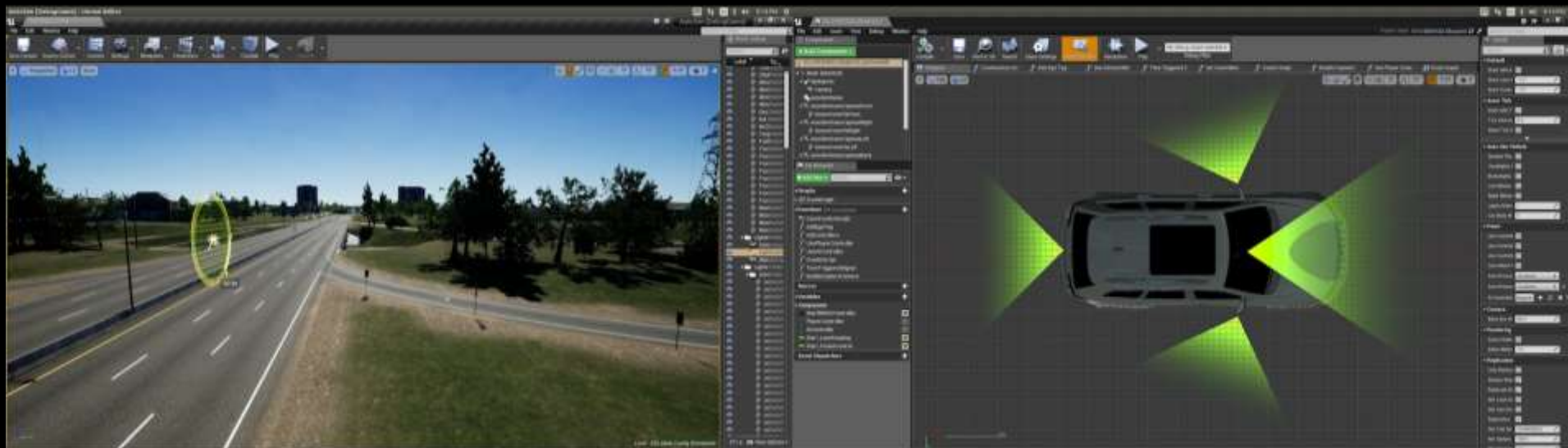
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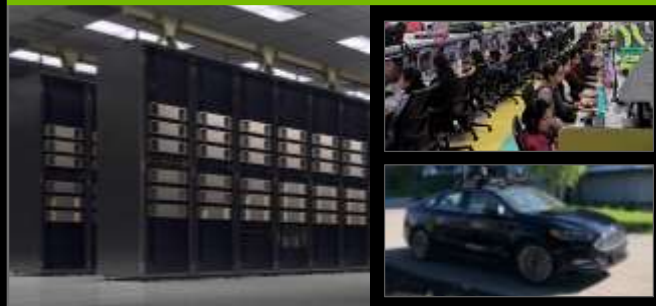
# MULTI-SENSOR SIMULATION



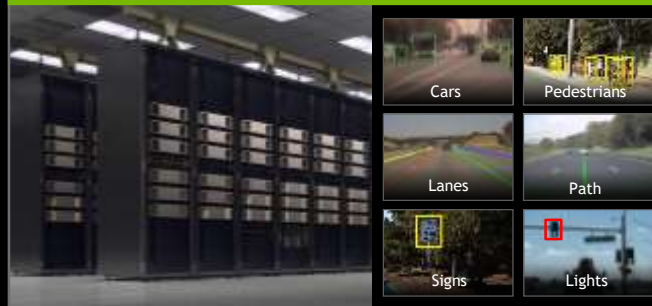
Setting Up The Environment

# NVIDIA DRIVE END-TO-END PLATFORM

## COLLECT & PROCESS DATA



## TRAIN MODELS



## SIMULATE



## DRIVE



# 370 PARTNERS DEVELOPING ON NVIDIA DRIVE



CARS



TRUCKS



MOBILITY  
SERVICES



SUPPLIERS



MAPPING



LIDAR



CAMERA /  
RADAR



STARTUPS

# KEY TAKEAWAYS

1. Understand end-to-end requirements of autonomous vehicle development
2. AI demands data center design built on dense GPU compute-at-scale
3. Consider the complete workflow of AI from experimentation to training to inference
4. Carefully weigh cost of productivity vs hardware cost alone = true TCO of DL
5. NVIDIA best practices leads to TSTADI reference platform  
(Training, Simulation, Testing for Autonomous Driving Infrastructure)



**THANK YOU**

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